

E4416A/E4417A EPM-P Series Power Meters and E-Series E9320 Peak and Average Power Sensors



EPM-P Power Meter Specifications

Specifications describe the instrument's warranted performance and apply after a 30 minute warm-up. These specifications are valid over its operating and environmental range unless otherwise stated and after performing a zero and calibration procedure.

Supplemental characteristics are intended to provide additional information; useful in applying the instrument by giving typical (expected), but not warranted performance parameters. These characteristics are shown in *italics* or labeled as 'typical', 'nominal' or 'approximate'.

Measurement uncertainties information can be found in, *Fundamentals of RF and Microwave Power Measurements, Application Note*, literature number 5965-6630E.

Compatibility, the EPM-P series power meters operate with the E-series E9320 family of power sensors for peak, average and time-gated power measurements. The EPM-P series also operates with the existing 8480 and N8480 series, E-series CW and the E9300 range of power sensors for average power measurements. For specifications pertaining to the 8480 and E-series CW and E9300 power sensors, please refer to the *EPM Series Power Meters, E-Series and 8480 Series Power Sensors, Technical Specification*, literature number 5965-6382E. For specifications pertaining to the N8480 series power sensors, please refer to the *N8480 Series Thermocouple Power Sensors, Technical Specification*, literature number 5989-9333EN.

Measurement modes, the EPM-P series power meters have two measurement modes:

- Normal mode (default mode using E9320 sensors) for peak, average and time-related measurements, and
- Average only mode. This mode is primarily for average power measurements on low-level signals, when using E9320 sensors, and is the mode used with 8480 and N8480 series sensors, E-series CW sensors and E-series E9300 sensors.

Frequency range: 9 kHz to 110 GHz, sensor dependent

Power range: -70 to +44 dBm, sensor dependent

Single Sensor Dynamic Range

| | |
|---|--|
| E-series E9320 peak and average power sensors | 70 dB maximum (normal mode) |
| | 85 dB maximum (average only mode) |
| E-series CW power sensors | 90 dB |
| E-series E9300 average power sensors | 80 dB maximum |
| 8480 series sensors | 50 dB maximum |
| N8480 series sensors | 55 dB maximum |
| Display units | |
| Absolute | Watts or dBm |
| Relative | Percent or dB |
| Display resolution | Selectable resolution of 1.0, 0.1, 0.01, 0.001 dB in logarithmic mode, or 1 to 4 significant digits in linear mode |
| Offset range | ± 100 dB in 0.001 dB increments, to compensate for external loss or gain |
| Video bandwidth | 5 MHz (set by meter and is sensor dependent) |

Note that the video bandwidth represents the ability of the power sensor and meter to follow the power envelope of the input signal. The power envelope of the input signal is, in some cases, determined by the signal's modulation bandwidth, and hence video bandwidth is sometimes referred to as modulation bandwidth.

Video bandwidth/dynamic range optimization

The power measurement system, comprising the sensor and meter, has its maximum video bandwidth defined by the E9320 sensor. To optimize the system's dynamic range for peak power measurements, the video bandwidth in the meter can be set to High, Medium and Low, as detailed in the following table. The filter video bandwidths stated in the table are not the 3 dB bandwidths as the video bandwidths are corrected for optimal flatness. Refer to Figures 6 to 8 for information on the sensor's peak flatness response. A filter OFF mode is also provided.

Table 1. Video bandwidth versus peak power dynamic range.

| Sensor model | Video bandwidth/Max peak power dynamic range | | | |
|------------------|--|----------------------------|----------------------------|----------------------------|
| | OFF | High | Medium | Low |
| E9321A E9325A | 300 kHz/−40 dBm to +20 dBm | 300 kHz/−42 dBm to +20 dBm | 100 kHz/−43 dBm to +20 dBm | 30 kHz/−45 dBm to +20 dBm |
| E9322A E9326A | 1.5 MHz/−37 dBm to +20 dBm | 1.5 MHz/−38 dBm to +20 dBm | 300 kHz/−39 dBm to +20 dBm | 100 kHz/−39 dBm to +20 dBm |
| E9323A E9327A | 5 MHz/−32 dBm to +20 dBm | 5 MHz/−32 dBm to +20 dBm | 1.5 MHz/−34 dBm to +20 dBm | 300 kHz/−36 dBm to +20 dBm |

Accuracy

Instrumentation

Please add the corresponding power sensor linearity percentage; see Tables 6a and 6b for the E9320 sensors.

| Average only mode | | |
|-------------------|-------------|-----------|
| Absolute | Logarithmic | ± 0.02 dB |
| | Linear | ± 0.5% |
| Relative | Logarithmic | ± 0.04 dB |
| | Linear | ± 1.0% |

| Normal mode | Calibration temperature ¹ ± 5 °C | Temperature 0 to 55 °C |
|----------------------------|---|------------------------|
| Absolute accuracy (log) | ± 0.04 dB | ± 0.08 dB |
| Absolute accuracy (linear) | ± 0.8% | ± 1.7% |
| Relative accuracy (log) | ± 0.08 dB | ± 0.16 dB |
| Relative accuracy (linear) | ± 1.6% | ± 3.4% |
| Time base accuracy | 0.01% | |

1 mW power reference

| | |
|----------------|---|
| Power output | 1.00 mW (0.0 dBm). Factory set to ± 0.5% traceable to the National Physical Laboratories (NPL), UK ² |
| Accuracy | For two years |
| | ± 0.5% (23 ± 3 °C) |
| | ± 0.6% (25 ± 10 °C) |
| | ± 0.9% (0 to 55 °C) |
| Frequency | 50 MHz nominal |
| SWR | 1.06 maximum (1.08 maximum for Option E41xA-003) |
| Connector type | Type N (f), 50 ohms |

¹ Power meter is within ± 5 °C of its calibration temperature.

² National metrology institutes of member states of the Metre Convention, such as the National Institute of Standards and Technology in the USA, are signatories to the Comité International des Poids et Mesures Mutual Recognition Arrangement. Further information is available from the Bureau International des Poids et Mesures, at <http://www.bipm.fr/>

Table 2. Measurement speed for different sensor types.

| Sensor type | | Measurement speed (readings/second) | | |
|---|--------------------------|-------------------------------------|-----|----------------------|
| | | Normal | x 2 | Fast ^{1, 2} |
| E-Series E9320 peak and average sensors | Average only mode | 20 | 40 | 400 |
| | Normal mode ³ | 20 | 40 | 1000 |
| E-Series CW and E9300 average power sensors | | 20 | 40 | 400 |
| 8480 and N8480 Series sensor | | 20 | 40 | NA |

| | |
|-------------------|---|
| Channel functions | A, B, A/B, B/A, A-B, B-A and Relative |
| Storage registers | 10 instrument states can be saved via the Save/Recall menu |
| Predefined setups | For common wireless standards (GSM900, EDGE, NADC, iDEN, <i>Bluetooth</i> [®] , IS-95 CDMA, W-CDMA and cdma2000 [®]), predefined setups are provided |

Trigger

| | |
|------------------|--|
| Sources | Internal, External TTL, GPIB, RS232/422 |
| Time resolution | 50 ns |
| Delay range | ± 1.0 s |
| Delay resolution | 50 ns for delays < ± 50 ms; otherwise 200 ns |
| Hold-off | |
| – Range | 1 µs to 400 ms |
| – Resolution | 1% of selected value (minimum of 100 ns) |

Internal Trigger

| | |
|----------------|-----------------|
| Range | –20 to +20 dBm |
| Level accuracy | ± 0.5 dB |
| Resolution | 0.1 dB |
| Latency | 500 ns ± 100 ns |

Latency is defined as the delay between the applied RF crossing the trigger level and the meter switching into the triggered state.

| | |
|------------------------|--|
| External trigger range | High > 2.0 V, Low < 0.8 V; BNC connector; rising or falling edge triggered; input impedance > 1 kW |
| Trigger out | Output provides TTL compatible levels (high > 2.4 V, low < 0.4 V) and uses a BNC connector |

¹ Fast speed is not available for 8480 and N8480 series sensors.

² Maximum measurement speed is obtained by using binary output in free run trigger.

³ For E9320 sensors, maximum speed is achieved using binary output in free run acquisition.

Sampling Characteristics

| | |
|--------------------|---------------------|
| Sampling rate | 20 Msamples/second |
| Sampling technique | Continuous sampling |

Rear Panel Inputs/Outputs

| | | |
|----------------------|--|------------------------------------|
| Recorder output(s) | Analog 0 to 1 V, 1 kW output impedance, BNC connector. Two outputs are available on E4417A (channels A and B). | |
| Remote input/output | | |
| – TTL output | Used to signal when measurement has exceeded a defined limit | |
| – TTL input | Initiates zero and calibration cycle | |
| Connector type | RJ-45 series shielded modular jack assembly | |
| – TTL output | High = 4.8 V max; Low = 0.2 V max. | |
| – TTL input | High = 3.5 V min, 5 V max; Low = 1 V max, –0.3 V min | |
| RS-232/422 interface | Serial interface for communication with an external controller. Male plug 9-pin D-subminiature connector. | |
| Trigger in | Accepts a TTL signal for initiating measurements, BNC connector | |
| Trigger out | Outputs a TTL signal for synchronizing with external equipment, BNC connector | |
| Ground | Binding post accepts 4 mm plug or bare wire connection | |
| Line power | Input voltage range | 85 to 264 Vac, automatic selection |
| | Input frequency range | 47 to 440 Hz |
| | Power requirement | Approximately 50 VA (14 Watts) |

Remote Programming

| | |
|--------------------|---|
| Interface | GPIB interface operates to IEEE 488.2 and IEC-625. RS-232 and RS-422 serial interfaces supplied as standard |
| Command language | SCPI standard interface commands |
| GPIB compatibility | SH1, AH1, T6, TE0, L4, LE0, SR1, RL1, PP1, DC1, DT1, C0. |

Environmental Specifications

| Operating environment | |
|-----------------------|--------------------------------|
| Temperature | 0 to 55 °C |
| Maximum humidity | 95% at 40 °C, (non-condensing) |
| Maximum altitude | 3,000 meters (9,840 feet) |

| Storage conditions | |
|--------------------------------|-------------------------------|
| Storage temperature | -20 to +70 °C |
| Non-operating maximum humidity | 90% at 65 °C (non-condensing) |
| Non-operating maximum altitude | 15,420 meters (50,000 feet) |

Regulatory Information

Electromagnetic compatibility

This product conforms with the protection requirements of European Council Directive 89/336/ EEC for Electromagnetic Compatibility (EMC). The conformity assessment requirements have been met using the technical Construction file route to compliance, using EMC test specifications EN 55011:1991 (Group 1, Class A) and EN 50082-1:1992. In order to preserve the EMC performance of the product, any cable which becomes worn or damaged must be replaced with the same type and specification.

Product safety

This product conforms to the requirements of European Council Directive 73/23/EEC, and meets the following safety standards:

- IEC/ EN 61010-1
- IEC 825-1 (1993) / EN 60825-1 (1994) Canada / CSA C22.2 No. 1010.1-93

Physical Specifications

| | | |
|------------|---|-------------------------------|
| Dimensions | The following dimensions exclude front and rear panel protrusions: 212.6 mm W x 88.5 mm H x 348.3 mm D (8.5 in x 3.5 in x 13.7 in) | |
| Weight | | |
| – Net | E4416A | 4.0 kg (8.8 lbs) approximate |
| | E4417A | 4.1 kg (9.0 lbs) approximate |
| – Shipping | E4416A | 7.9 kg (17.4 lbs) approximate |
| | E4417A | 8.0 kg (17.6 lbs) approximate |

Ordering Information

Standard-shipped accessories

| Power sensor cable | |
|--------------------|--|
| E9288A | 1.5 meter (5 ft). One per E4416A, two per E4417A |
| Power cord | One 2.4 meter (7.5 ft) cable. Power plug matches destination requirements. |
| Manuals | Product CD-ROM (contains English and localized User's Guide and Programming Guide) |

Power Meter Options

| Connectors | |
|---|--|
| E441xA-002 | Parallel rear panel sensor input connector(s) and front panel reference calibrator connector |
| E441xA-003 | Parallel rear panel sensor input connector(s) and rear panel reference calibrator connector |
| Calibration documentation | |
| E441xA-A6J | NSI/ NCSL Z540-1-1994 compliant calibration test data including measurement uncertainties |
| E441xA-1A7 | ISO/ IEC 17025:2005 compliant calibration test data including measurement uncertainties |
| Power sensor cables | |
| E441xA-004 | E441xA-004 |
| For operation with the E9320 power sensors | |
| E9288A | E9288A |
| E9288B | E9288B |
| E9288C | E9288C |
| Note: The E9288A, B, and C sensor cables will also operate with 8480, N8480 and E-series power sensors. | |

For operation with 8480, N8480, E-series CW and E9300 power sensors

| | |
|--------|---|
| 11730A | Power sensor and SNS noise source cable, length 5 ft (1.5 m) |
| 11730B | Power sensor and SNS noise source cable, length 10 ft (3 m) |
| 11730C | Power sensor and SNS noise source cable, length 20 ft (6.1 m) |
| 11730D | Power sensor cable, length 50 ft (15.2 m) |
| 11730E | Power sensor cable, length 100 ft (30.5 m) |
| 11730F | Power sensor cable, length 200 ft (61.0 m) |

Other sensor cable lengths can be supplied on request

Accessories

| | |
|------------|--|
| E441xA-908 | Rack mount kit (one instrument) |
| E441xA-909 | Rack mount kit (two instruments) |
| 34131A | Transit case for half-rack 2U high instruments |
| 34141A | Yellow soft carry/operating case |
| 34161A | Accessory pouch |

Service Options

Calibration ¹

| | |
|-------------|---|
| R-50C-011-3 | R-50C-011-3 Keysight Calibration Upfront Plan 3-year coverage |
| R-50C-011-5 | R-50C-011-5 Keysight Calibration Upfront Plan 5-year coverage |

E-Series E9320 Power Sensor Specifications

The E9320 peak and average power sensors are designed for use with the EPM-P series power meters. The E9320 sensors have two measurement modes:

| | |
|-------------------|---|
| Normal mode | Default mode for E9320 sensors for peak, average and time-related measurements |
| Average only mode | Designed primarily for average power measurements on low-level signals. This mode is the only mode used with 8480 and N8480 series sensors, E-series CW sensors and E-series E9300 sensors. |

The following specifications are valid after zero and calibration of the power meter.

Note: E9320 power sensors MUST be used with an E9288A, B or C cable.

¹ Options not available in all countries.

Table 3. Sensor specification.

| Sensor model | Video bandwidth | Frequency range | Power range | | Maximum power | Connector type |
|--|-----------------|-------------------------------------|-----------------------|-----------------------|---|----------------|
| Average only mode Normal mode ¹ | | | | | | |
| E9321A E9325A | 300 kHz | 50 MHz to 6 GHz 50 MHz to 18 GHz | -65 dBm to +20 dBm | -50 dBm to +20 dBm | +23 dBm average; +30 dBm peak (< 10 µsec duration) | Type N (m) |
| E9322A E9326A | 1.5 MHz | 50 MHz to 6 GHz 50 MHz to 18 GHz | -60 dBm to +20 dBm | -45 dBm to +20 dBm | | |
| E9323A E9327A | 5 MHz | 50 MHz to 6 GHz 50 MHz to 18 GHz | -60 dBm to +20 dBm | -40 dBm to +20 dBm | | |

The E9320 power sensors have two measurement ranges (lower and upper) as detailed in Table 4.

Table 4. Lower and upper measurement ranges.

| | E9321A/E9325A | | E9322A/E9326A | | E9323A/E9327A | |
|---------------------------------|---------------|------------------------|---------------|------------------------|---------------|------------------------|
| | Normal | Average only | Normal | Average only | Normal | Average only |
| Lower range (min. power) | -50 dBm | -65 dBm | -45 dBm | -60 dBm | -40 dBm | -60 dBm |
| Lower range (max. power) | +0.5 dBm | -17.5 dBm ¹ | -5 dBm | -13.5 dBm ² | -5 dBm | -10.5 dBm ² |
| Lower to upper auto range point | | | | | | |
| Upper to lower auto range point | -9.5 dBm | -18.5 dBm | -15 dBm | -14.5 dBm | -15 dBm | -11.5 dBm |
| Upper range (min. power) | -35 dBm | -50 dBm | -35 dBm | -45 dBm | -30 dBm | -35 dBm |
| Upper range (max. power) | +20 dBm | +20 dBm ¹ | +20 dBm | +20 dBm ² | +20 dBm | +20 dBm ² |

¹ For average power measurements, free run acquisition.

² Applies to CW and constant amplitude signals only above -20 dBm.

Table 5. Power sensor maximum SWR.

| Sensor model | Maximum SWR (≤ 0 dBm) | |
|----------------|-----------------------------|------|
| E9321A, E9325A | 50 MHz to 2 GHz | 1.12 |
| | >2 GHz to 10 GHz | 1.16 |
| | >10 GHz to 16 GHz | 1.23 |
| | >16 GHz to 18 GHz | 1.28 |
| E9322A, E9326A | 50 MHz to 2 GHz | 1.12 |
| | >2 GHz to 12 GHz | 1.18 |
| | >12 GHz to 16 GHz | 1.21 |
| | >16 GHz to 18 GHz | 1.27 |
| E9323A, E9327A | 50 MHz to 2 GHz | 1.14 |
| | >2 GHz to 16 GHz | 1.22 |
| | >16 GHz to 18 GHz | 1.26 |

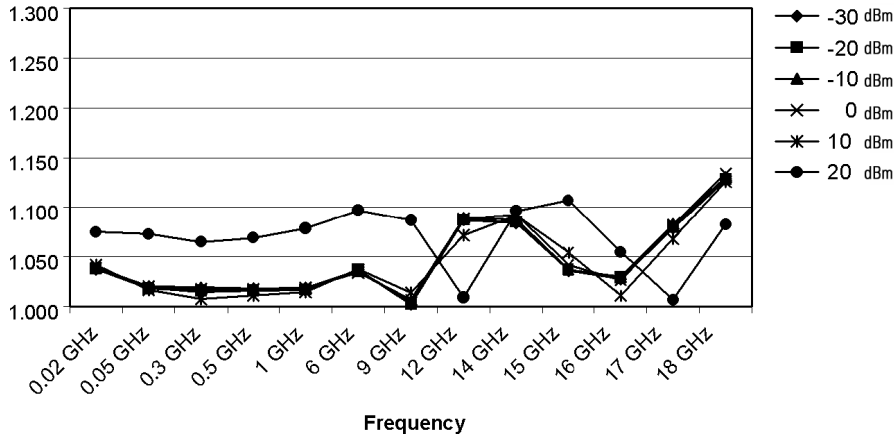


Figure 1. Typical SWR for the E9321A and E9325A sensors at various power levels.

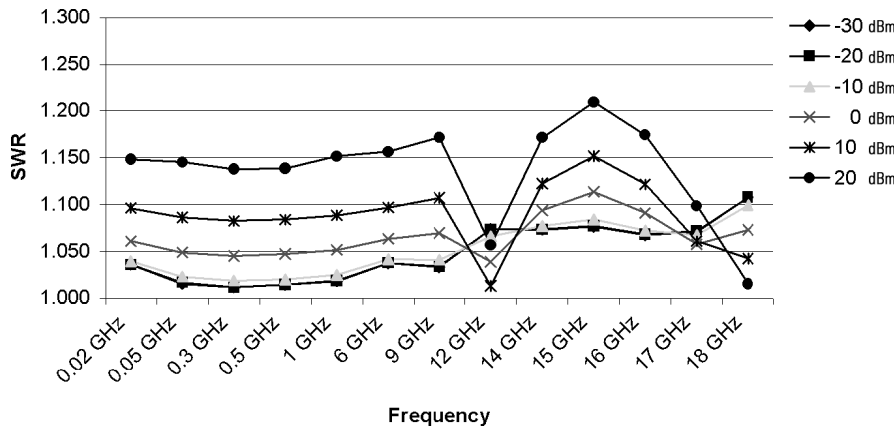


Figure 2. Typical SWR for the E9322A and E9326A sensors at various power levels.

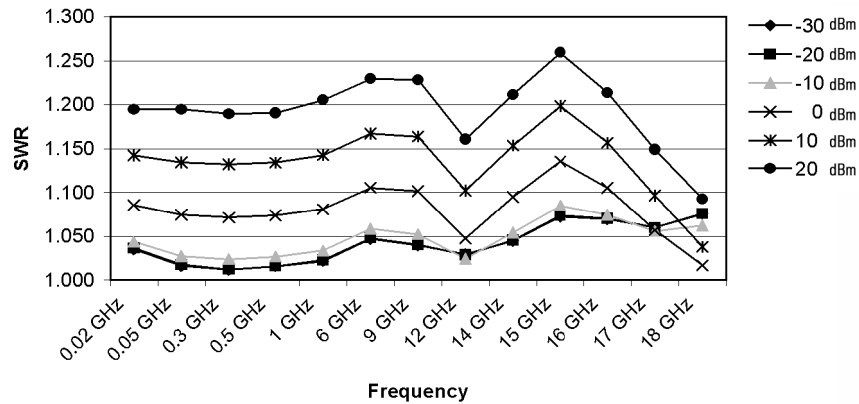


Figure 3. Typical SWR for the E9323A and E9327A sensors at various power levels.

Sensor Linearity

Table 6a. Power sensor linearity, normal mode (upper and lower range).

| Sensor model | Temperature (25 ± 10 °C) | Temperature (0 to 55 °C) |
|-------------------|--------------------------|--------------------------|
| E9321A and E9325A | ± 4.2% | ± 5.0% |
| E9322A and E9326A | ± 4.2% | ± 5.0% |
| E9323A and E9327A | ± 4.2% | ± 5.0% |

Table 6b. Power sensor linearity, average only mode (upper and lower range).

| Sensor model | Temperature (25 ± 10 °C) | Temperature (0 to 55 °C) |
|-------------------|--------------------------|--------------------------|
| E9321A and E9325A | ± 3.7% | ± 4.5% |
| E9322A and E9326A | ± 3.7% | ± 4.5% |
| E9323A and E9327A | ± 3.7% | ± 5.0 % |

If the sensor temperature changes after calibration, and the meter and sensor is not re-calibrated, then the following additional linearity errors should be added to the linearity figures in Tables 6a and 6b.

Table 6c. Additional linearity error (normal and average only modes).

| Sensor model | Temperature (25 ± 10 °C) | Temperature (0 to 55 °C) |
|-------------------|--------------------------|--------------------------|
| E9321A and E9325A | ± 1.0% | ± 1.0% |
| E9322A and E9326A | ± 1.0% | ± 1.0% |
| E9323A and E9327A | ± 1.0% | ± 1.0% |

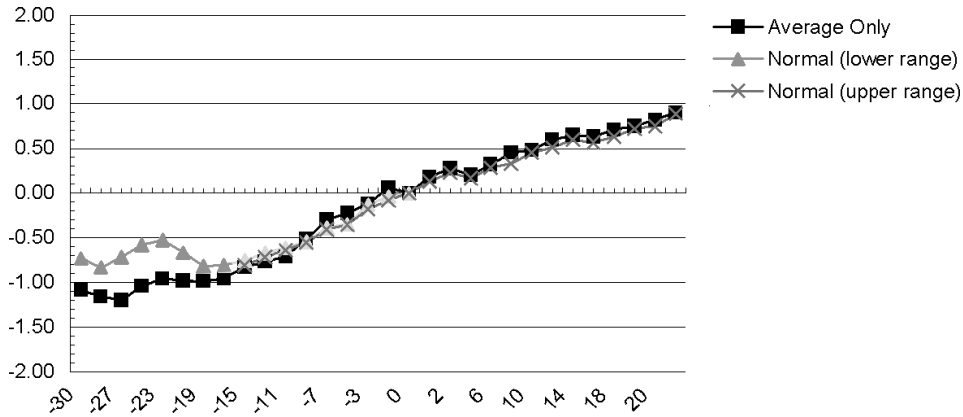


Figure 4. Typical power linearity at 25 °C for the E9323A and E9327A 5 MHz bandwidth sensors, after zero and calibration, with associated measurement uncertainty.

| Power range | -30 to -20 dBm | -20 to -10 dBm | -10 to 0 dBm | 0 to +10 dBm | +10 to +20 dBm |
|-------------------------|----------------|----------------|--------------|--------------|----------------|
| Measurement uncertainty | 0.9% | 0.8% | 0.65% | 0.55% | 0.45% |

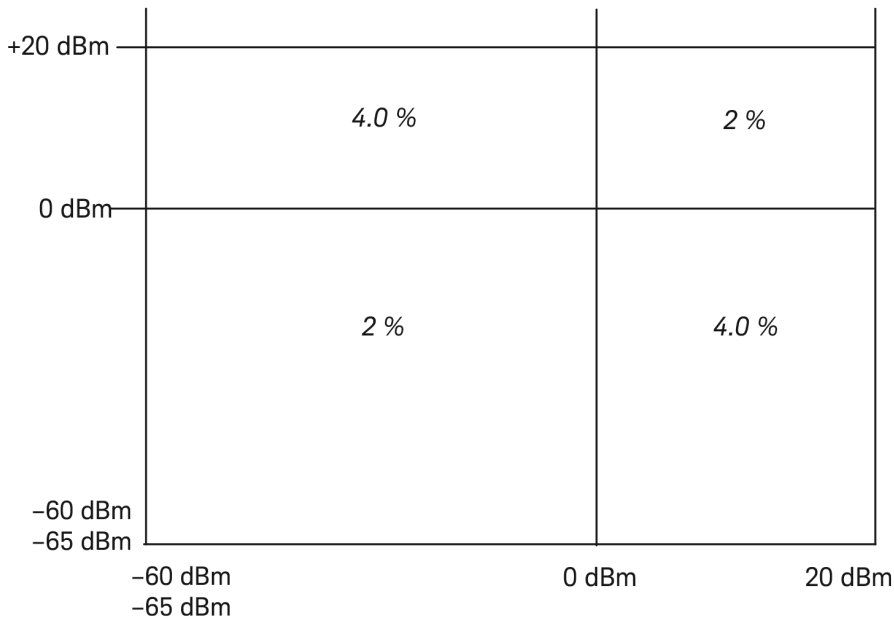


Figure 5. Relative mode power measurement linearity with an EPM-P series power meter, at 25 °C (typical).

Figure 5 shows the typical uncertainty in making a relative power measurement, using the same power meter channel and the same power sensor to obtain the reference and the measured values. It also assumes that negligible change in frequency and mismatch error occurs when transitioning from the power level used as the reference to the power level measured.

Peak Flatness

The peak flatness is the flatness of a peak-to-average ratio measurement for various tone- separations for an equal magnitude two-tone RF input. Figures 6, 7 and 8 refer to the relative error in peak-to-average measurement as the tone separation is varied. The measurements were performed at -10 dBm average power using an E9288A sensor cable (1.5 m).

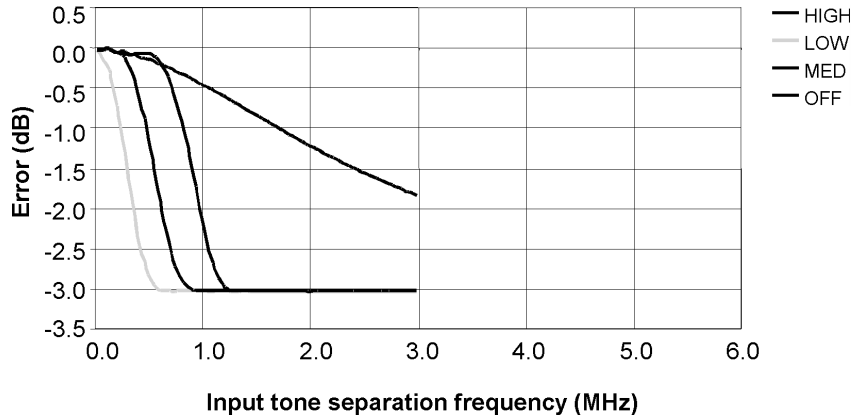


Figure 6. E9321A and E9325A Error in peak-to-average measurements for a two-tone input (high, medium, low and off filters).

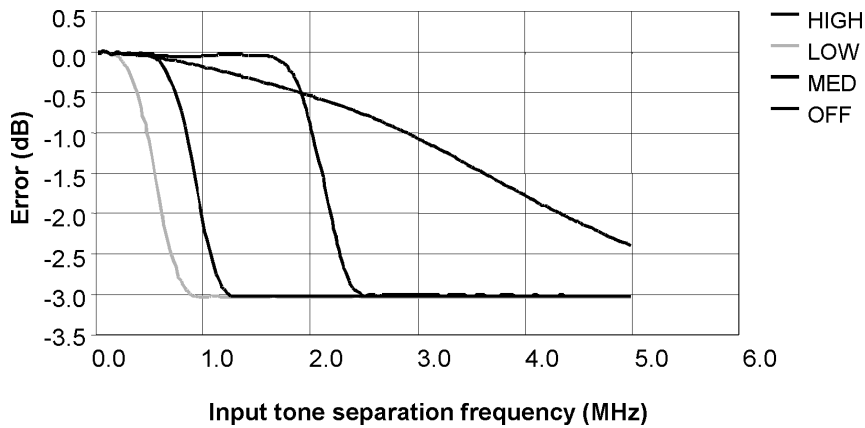


Figure 7. E9322A and E9326A error in peak-to-average measurements for a two-tone input (high, medium, low and off filters).

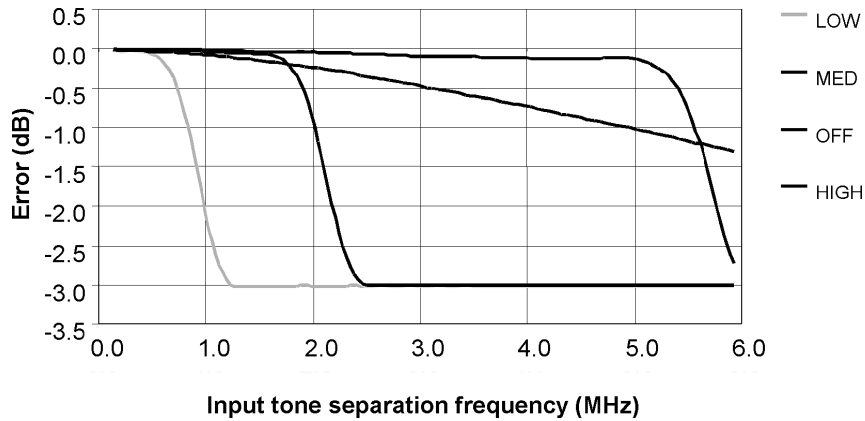


Figure 8. E9323A and E9327A error in peak-to-average measurements for a two-tone input (high, medium, low and off filters).

Calibration Factor (CF) and Reflection Coefficient (Rho)

Calibration Factor and Reflection Coefficient data are provided at frequency intervals on a data sheet included with the power sensor. This data is unique to each sensor. If you have more than one sensor, match the serial number on the data sheet with the serial number of the power sensor you are using. The CF corrects for the frequency response of the sensor. The EPM-P series power meter automatically reads the CF data stored in the sensor and uses it to make corrections.

For power levels greater than 0 dBm, add to the calibration factor uncertainty specification:

- $\pm 0.1\%/dB$ (for E9321A and E9325A sensors),
- $\pm 0.15\%/dB$ (for E9322A and E9326A sensors) and
- $\pm 0.2\%/dB$ (for E9323A and E9327A sensors)

Reflection Coefficient (Rho) relates to the SWR according to the formula:

- $SWR = (1 + Rho)/(1 - Rho)$

Maximum relative uncertainties of the CF data are listed in Table 7. The uncertainty analysis for the calibration of the sensors was done in accordance with the ISO Guide. The uncertainty data, reported on the calibration certificate, is the expanded uncertainty with a 95% confidence level and a coverage factor of 2.

Table 7. Calibration factor relative uncertainty at 0.1 mW (–10 dBm).

| Frequency | Uncertainty (%) (25 ± 10 °C) ¹ | Uncertainty (%) (0 to 55 °C) ¹ |
|-----------|---|---|
| 50 MHz | Reference | Reference |
| 100 MHz | 1.8 | 2.0 |
| 300 MHz | 1.8 | 2.0 |
| 500 MHz | 1.8 | 2.0 |
| 800 MHz | 1.8 | 2.0 |
| 1.0 GHz | 2.1 | 2.3 |
| 1.2 GHz | 2.1 | 2.3 |
| 1.5 GHz | 2.1 | 2.3 |
| 2.0 GHz | 2.1 | 2.3 |
| 3.0 GHz | 2.1 | 2.3 |
| 4.0 GHz | 2.1 | 2.3 |
| 5.0 GHz | 2.1 | 2.3 |
| 6.0 GHz | 2.1 | 2.3 |
| 7.0 GHz | 2.3 | 2.5 |
| 8.0 GHz | 2.3 | 2.5 |
| 9.0 GHz | 2.3 | 2.5 |
| 10.0 GHz | 2.3 | 2.5 |
| 11.0 GHz | 2.3 | 2.5 |
| 12.0 GHz | 2.3 | 2.5 |
| 12.4 GHz | 2.3 | 2.5 |
| 13.0 GHz | 2.3 | 2.5 |
| 14.0 GHz | 2.5 | 2.8 |
| 15.0 GHz | 2.5 | 2.8 |
| 16.0 GHz | 2.5 | 2.8 |
| 17.0 GHz | 2.5 | 2.8 |
| 18.0 GHz | 2.5 | 2.8 |

¹ The characterized calibration factor should not deviate between periodic calibrations by more than the specified maximum uncertainty in the table. Compliance is confirmed by the relative deviation ($\frac{|CF_1 - CF_2|}{CF_1} * 100$) being less than or equal to $\sqrt{2}$ times the specified maximum uncertainty, $\sqrt{2} * U_{max}$ with a reference calibration factor of 100%.

Zero Set

This specification applies to a ZERO performed when the sensor input is not connected to the POWER REF.

Table 8. Zero set.

| Sensor model | Zero set (normal mode) | Zero set (average only mode) |
|----------------|------------------------|------------------------------|
| E9321A, E9325A | 5 nW | 0.17 nW |
| E9322A, E9326A | 19 nW | 0.5 nW |
| E9323A, E9327A | 60 nW | 0.6 nW |

Zero Drift and Measurement Noise

Table 9. Zero drift and measurement noise.

| Sensor model | Zero drift ¹ | | Measurement noise ² | | |
|----------------|-------------------------|-------------------|--------------------------------|--------------------------|-------------------|
| | Normal mode | Average only mode | Normal mode ³ | Normal mode ⁴ | Average only mode |
| E9321A, E9325A | < 5 nW | < 60 pW | < 6 nW | < 75 nW | < 165 pW |
| E9322A, E9326A | < 5 nW | < 100 pW | < 12 nW | < 180 nW | < 330 pW |
| E9323A, E9327A | < 40 nW | < 100 pW | < 25 nW | < 550 nW | < 400 pW |

Effect of averaging on noise: Averaging over 1 to 1024 readings is available for reducing noise. Table 9 provides the measurement noise for a particular sensor. Use the noise multipliers in Table 10, for the appropriate speed (normal or x 2) or measurement mode (normal or average only) and the number of averages, to determine the total measurement noise value.

In addition, for x 2 speed (in normal mode) the total measurement noise should be multiplied by 1.2, and for fast speed (in normal mode), the multiplier is 3.4.

Note that in fast speed, no additional averaging is implemented.

¹ Within 1 hour after zero set, at a constant temperature, after a 24-hour warm-up of the power meter.

² Measured over a one-minute interval, at a constant temperature, two standard deviations, with averaging set to 1 (for normal mode), 16 (for average only mode, normal speed) and 32 (for average only mode, x 2 speed).

³ In free run acquisition mode.

⁴ Noise per sample, video bandwidth set to OFF with no averaging (i.e. averaging set to 1) - see the note "Effect of Video Bandwidth Setting" and Table 11.

Table 10. Noise multipliers.

| Mode | Number of averages | 1 | 2 | 4 | 8 | 16 | 32 | 64 | 128 | 256 | 512 | 1024 |
|--------------|---|-----|------|------|------|------|------|------|------|------|------|------|
| Average-only | Noise multiplier (normal speed) | 5.5 | 3.89 | 2.75 | 1.94 | 1.0 | 0.85 | 0.61 | 0.49 | 0.34 | 0.24 | 0.17 |
| | Noise multiplier (x 2 speed) | 6.5 | 4.6 | 3.25 | 2.3 | 1.63 | 1.0 | 0.72 | 0.57 | 0.41 | 0.29 | 0.2 |
| Normal | Noise multiplier (normal speed; free run acquisition) | 1.0 | 0.94 | 0.88 | 0.82 | 0.76 | 0.70 | 0.64 | 0.58 | 0.52 | 0.46 | 0.40 |

Example

E9321A power sensor, number of averages = 4, free run acquisition, normal mode, x 2 speed.
 Measurement noise calculation: ($< 6 \text{ nW} \times 0.88 \times 1.2$) = $< 6.34 \text{ nW}$

Effect of video bandwidth setting

The noise per sample is reduced by applying the meter video bandwidth reduction filter setting (High, Medium or Low). If averaging is implemented, this will dominate any effect of changing the video bandwidth.

Table 11. Effect of video bandwidth on noise per sample.

| Sensor | Noise multipliers | | |
|----------------|-------------------|--------|------|
| | Low | Medium | High |
| E9321A, E9325A | 0.32 | 0.50 | 0.63 |
| E9322A, E9326A | 0.50 | 0.63 | 0.80 |
| E9323A, E9327A | 0.40 | 0.63 | 1.0 |

Example

E9322A power sensor, triggered acquisition, video bandwidth = High. Noise per sample calculation:
 ($< 180 \text{ nW} \times 0.80$) = $< 144 \text{ nW}$

Effect of time-gating on measurement noise

The measurement noise will depend on the time gate length, over which measurements are made. Effectively 20 averages are carried out every 1 us of gate length.

Settling Times

Average-only mode

In normal and x 2 speed, manual filter, 10 dB decreasing power step refer to Table 12.

Table 12. Settling time (average only mode).

| Number of average | 1 | 2 | 4 | 8 | 16 | 32 | 64 | 128 | 256 | 512 | 1024 |
|-------------------------|------|------|------|------|------|-----|-----|-----|-----|-----|------|
| Settling time(s) normal | 0.08 | 0.13 | 0.24 | 0.45 | 1.1 | 1.9 | 3.5 | 6.7 | 14 | 27 | 57 |
| Settling time(s) x 2 | 0.07 | 0.09 | 0.15 | 0.24 | 0.45 | 1.1 | 1.9 | 3.5 | 6.7 | 14 | 27 |

In fast speed, within the range –50 to +20 dBm, for a 10 dB decreasing power step, the settling time is 10 ms (for the E4416A) and 20 ms (for the E4417A).

When a power step crosses the power sensor's auto-range switch point, add 25 ms.

Normal mode

In normal, free run acquisition mode, within the range –20 to +20 dBm, for a 10 dB decreasing power step, the settling time is dominated by the measurement update rate and is listed in Table 13 for various filter settings.

Table 13. Settling time (normal mode).

| Number of averages | 1 | 2 | 4 | 8 | 16 | 32 | 64 | 128 | 256 | 512 | 1024 |
|--|------|------|------|------|------|-----|-----|-----|------|------|------|
| Settling time free run acquisition, normal speed (s) | 0.1 | 0.15 | 0.25 | 0.45 | 0.9 | 1.7 | 3.3 | 6.5 | 13.0 | 25.8 | 51.5 |
| Settling time free run acquisition, X2 speed (s) | 0.08 | 0.1 | 0.15 | 0.25 | 0.45 | 0.9 | 1.7 | 3.3 | 6.5 | 13.0 | 25.8 |

In normal mode, measuring in continuous or single acquisition mode, the performance of rise times, fall times and 99% settled results are shown in Table 14. Rise time and fall time specifications are for a 0.0 dBm pulse, with the rise time and fall time measured between 10% to 90% points and upper range selected.

Table 14. Rise and fall times versus sensor bandwidth. ¹

| Sensor mode, parameter | | Video bandwidth setting | | | |
|------------------------|--------------------------------|-------------------------|--------|------|-----|
| | | Low | Medium | High | Off |
| E9321A | rise time (< μs) | 2.6 | 1.5 | 0.9 | 0.3 |
| E9325A | fall time (< μs) | 2.7 | 1.5 | 0.9 | 0.5 |
| | Settling time (rising) (< μs) | 5.1 | 5.1 | 4.5 | 0.6 |
| | Settling time (falling) (< μs) | 5.1 | 5.1 | 4.5 | 0.9 |
| | rise time (< μs) | 1.5 | 0.9 | 0.4 | 0.2 |
| E9322A | fall time (< μs) | 1.5 | 0.9 | 0.4 | 0.3 |
| E9326A | Settling time (rising) (< μs) | 5.3 | 4.5 | 3.5 | 0.5 |
| | Settling time (falling) (< μs) | 5.3 | 4.5 | 3.5 | 0.9 |
| | rise time (< μs) | 0.9 | 0.4 | 0.2 | 0.2 |
| | fall time (< μs) | 0.9 | 0.4 | 0.2 | 0.2 |
| E9323A | Settling time (rising) (< μs) | 4.5 | 3.5 | 1.5 | 0.4 |
| E9327A | Settling time (falling) (< μs) | 4.5 | 3.5 | 2 | 0.4 |

Overshoot in response to power steps with fast rise times, i.e. less than the sensor rise time, is < 10%.
 When a power step crosses the power sensor's auto-range switch point, add 10 μs.

¹ Rise and fall time specifications are only valid when used with the E9288A sensor cable (1.5 meters).

Physical Specifications

| | |
|---------------------------|--|
| Dimensions | 150 mm L x 38 mm W x 30 mm H (5.9 in x 1.5 in x 1.2 in) |
| Weight | Net: 0.2 kg (0.45 lbs) |
| Shipping | 0.55 kg (1.2 lbs) |
| Mechanical characteristic | Mechanical characteristics such as center conductor protrusion and pin depth are not performance specifications. They are, however, important supplemental characteristics related to electrical performance. At no time should the pin depth of the connector be protruding |

Ordering Information

| | |
|--------|------------------------------|
| E9321A | 50 MHz to 6 GHz; 300 kHz BW |
| E9322A | 50 MHz to 6 GHz; 1.5 MHz BW |
| E9323A | 50 MHz to 6 GHz; 5 MHz BW |
| E9325A | 50 MHz to 18 GHz; 300 kHz BW |
| E9326A | 50 MHz to 18 GHz; 1.5 MHz BW |
| E9327A | 50 MHz to 18 GHz; 5 MHz BW |

Power Sensor Options

| | |
|------------|--|
| E932xA-A6J | Supplies ANSI/NCSL Z540-1-1994 test data including measurement uncertainties |
| E932xA-1A7 | Supplies ISO/ IEC 17025:2005 test data including measurement uncertainties |

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